A splitting line model for directional relations

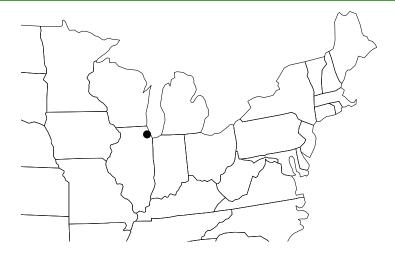
Kevin Buchin¹ Vincent Kusters² Bettina Speckmann¹ Frank Staals³ Bogdan Vasilescu¹

¹Eindhoven University of Technology

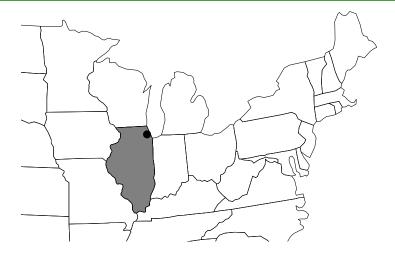
²ETH Zürich

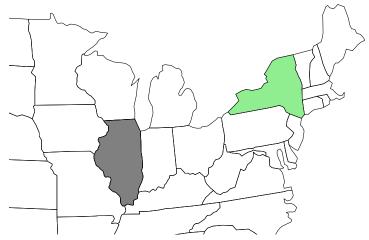
³Utrecht University

November 3, 2011

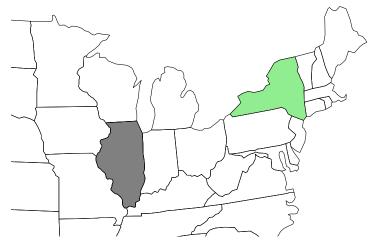


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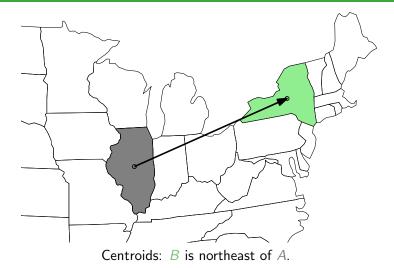




Where is New York with respect to Illinois?

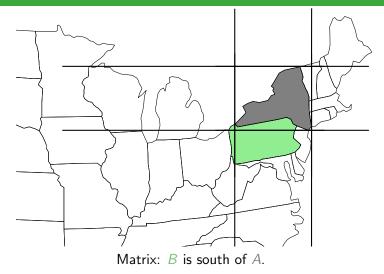


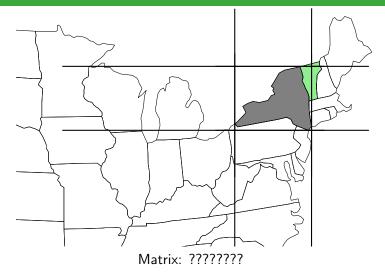
Where is target polygon B with respect to reference polygon A?



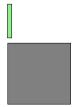


Centroids: B is southwest of A.





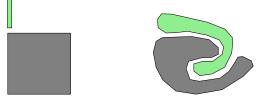
Directional relations are subjective



North or northwest?

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Directional relations are subjective

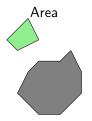


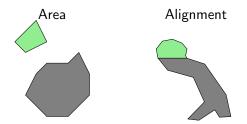
North or northwest? North, northeast, or east?

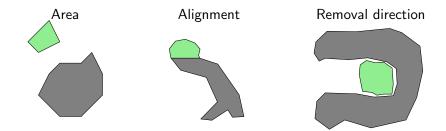
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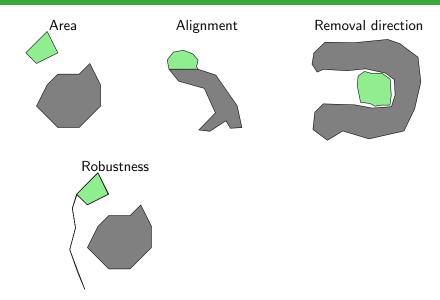
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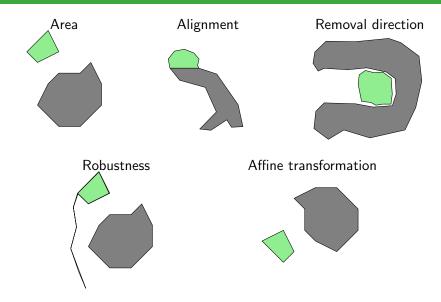




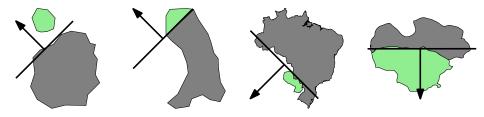




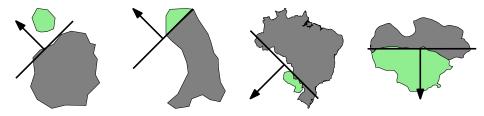




A splitting line for directional relations

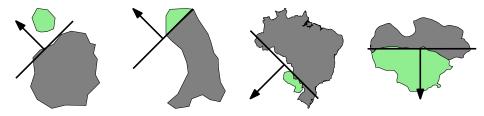


A splitting line for directional relations



Our Approach: Compute the best splitting line that separates *A* and *B*.

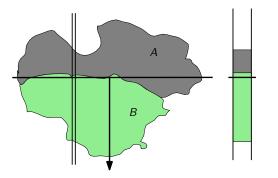
A splitting line for directional relations



Our Approach: Compute the best splitting line that separates *A* and *B*.

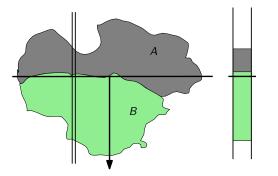
Question: What does it mean to be the best splitting line?

Measuring the quality of a splitting line



- Divide the scene in slabs
- Compute the quality of each slab.

Measuring the quality of a splitting line



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$$M_{line}(y) = \int_{-\infty}^{\infty} M(x,y) dx$$

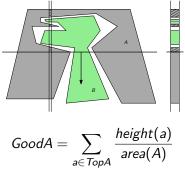
User definable parameters.

 $M = \rho_{1} \cdot f(B) \cdot GoodA + \\\rho_{1} \cdot g(A) \cdot GoodB - \\\rho_{2} \cdot h(B) \cdot AlignmentA - \\\rho_{3} \cdot ObstructA - \rho_{3} \cdot ObstructB$

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criterion: Area

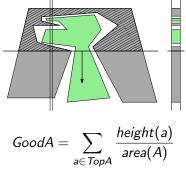
Measures the amount of *A* on the *A*-side.



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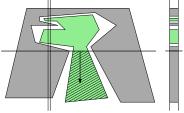
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Measures the amount of B on the B-side.



 $M = \rho_{1} \cdot f(B) \cdot GoodA + \rho_{1} \cdot g(A) \cdot GoodB - \rho_{2} \cdot h(B) \cdot AlignmentA - \rho_{3} \cdot ObstructA - \rho_{3} \cdot ObstructB$

criterion: Alignment

Measures the alignment of ℓ with A.

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 $M = \rho_{1} \cdot f(B) \cdot GoodA + \\\rho_{1} \cdot g(A) \cdot GoodB - \\\rho_{2} \cdot h(B) \cdot AlignmentA - \\\rho_{3} \cdot ObstructA - \rho_{3} \cdot ObstructB$

criterion: Removal direction.

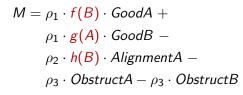
Measures the ease with which A can be moved away from B.

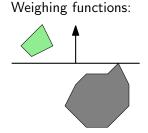
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criterion: Removal direction.

Measures the ease with which B can be moved away from A.

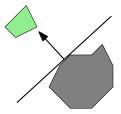
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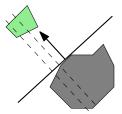
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Weighing functions:



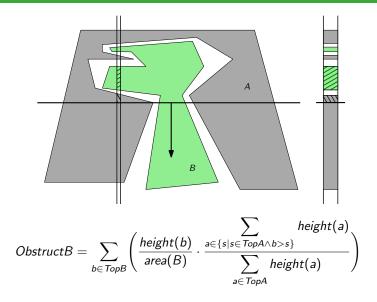
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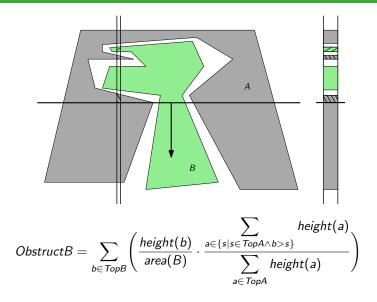
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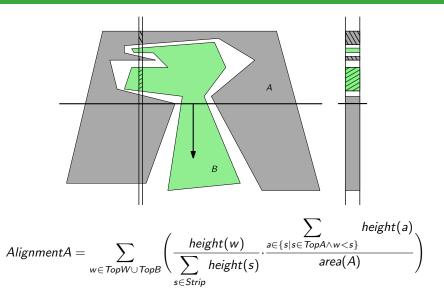


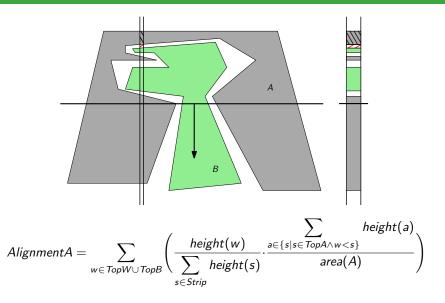
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How about Robustness and Affine transformation?









Observation: $M_{line}(y)$ maximal if $\frac{d}{dy}M_{line}(y) = 0$.

ALGORITHM Sweep ℓ downwards and compute a description of M_{line} and its derivative.

$\int GoodA(y,x)dx$ is a piecewise quadratic function in y:



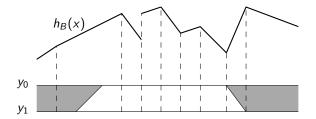
$\int GoodA(y,x)dx$ is a piecewise quadratic function in y:



Maintain set P of trapezoids intersected by ℓ .

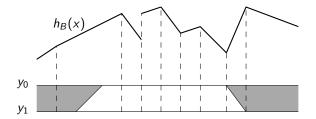
P changes at most n times $\implies O(n \log n)$ to compute GoodA.

 $\int ObstructB(y, x)dx$ is the sum of rational functions in y:



Maintain $h_B(x)$: the amount of B above the sweep line.

 $\int ObstructB(y, x)dx$ is the sum of rational functions in y:



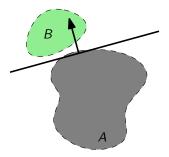
Maintain $h_B(x)$: the amount of *B* above the sweep line. $O(n^2)$ events $\Longrightarrow O(n^2 \log n)$ to compute *ObstructB*.

Question: Which directions should we use?

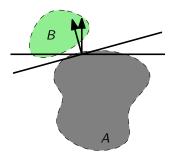
• Use the 8 compass directions N,NE,E,..,NW

- Use the 8 compass directions N,NE,E,...,NW
- Use k > 8 directions (for example k = 360)

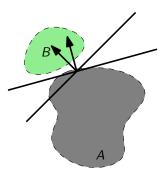
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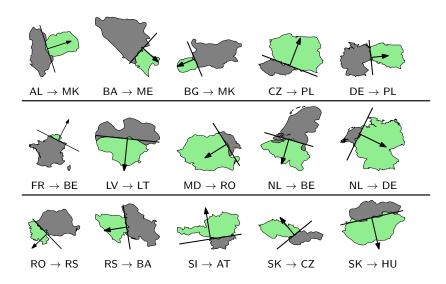
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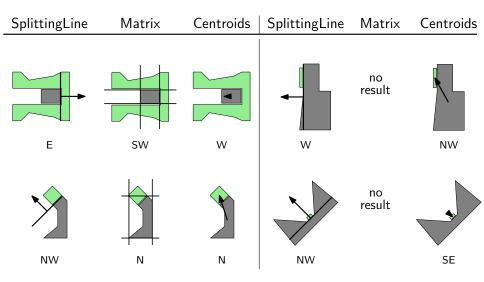
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Optimal splitting lines using 360 directions

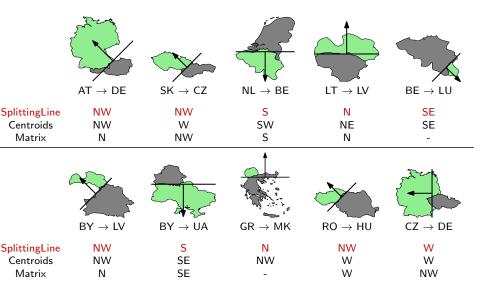


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Splitting lines for directional relations



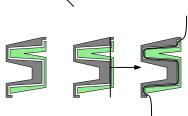
 8 directions vs many directions



 8 directions vs many directions



• Non-linear separator (e.g. curve or polyline)



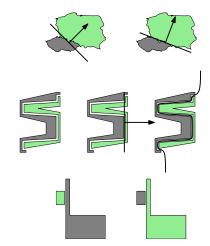
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 8 directions vs many directions

• Non-linear separator (e.g. curve or polyline)

Are directional relations

(a)symmetric?



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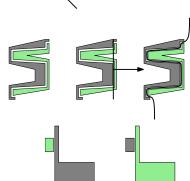
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Thank you! Questions?