Grouping Time-varying Data for Interactive Exploration

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1) Define an $(\alpha, \beta, ..., \eta)$ -pattern



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2) Design an efficient algorithm ALG(Input)



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Detecting maximal groups in trajectory data

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 \checkmark (*m*, ε , δ)-group

- $m = \min \text{ size}$
- $\varepsilon = \max \operatorname{dist}$
- $\delta = \min duration$



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- ✓ Running time: $O(n^3 \tau)$
 - n = #trajectories
 - $\tau = {\rm trajectory} \ {\rm length}$
- ✓ Trajectory Grouping Structure [WADS 2013]



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Assumption:

The practicioner knows the right parameter values.

 $\checkmark (m, \varepsilon, \delta) - \text{group}$ $m = \min \text{size}$

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 $\delta = \delta_1 \blacksquare \llbracket [t_4, t_6]$

The practicioner does not know the right parameter values

 \implies We need to be able to change the parameters efficiently

Goal: Change parameters (m, ε, δ) to $(m', \varepsilon', \delta')$

 \Longrightarrow Report only the maximal groups that have changed

- Maximal (m, ε, δ) groups that are not maximal $(m', \varepsilon', \delta')$ groups
- Maximal $(m', \varepsilon', \delta')$ groups that are not maximal (m, ε, δ) groups

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t3

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 $G = \blacksquare$ is a (m, ε, δ) -group on $I = [t_1, t_3]$

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 $-t_{\alpha}$

L1

 $t_3 + t_\beta$

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 is a (m, ε, δ) -group on $I = [t_1, t_3]$
 \blacksquare is a $(m, \varepsilon', \delta)$ -group on $I' = [t_1 - t_\alpha, t_3 + t_\beta]$
Intuitively, (G, I) and (G, I') are the same group.

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Intuitively, (G, I') and (G, I'') are different groups.



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Intuitively, (G, I') and (G, I'') are different groups.

■ is a $(m, \varepsilon_>, \delta)$ -group on $I_> \supset I \cup I'$ Intuitively, $(G, I_>)$ is different from (G, I') and from (G, I'')











 \mathbb{R}^1

m = 1

 $\delta = 0$

Consider region A_G s.t.:

 $(\varepsilon, t) \in A_G \iff G$ forms an (m, ε, δ) -group at time t





G = some of entites

 $\begin{array}{l} m = 1 \\ \delta = 0 \end{array} \qquad \qquad \text{Consider region } A_G \text{ s.t.:} \end{array}$

 \mathbb{R}^1

 $(\varepsilon, t) \in A_G \iff G$ is ε -connected at time t



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- G =some of entites $H \supset G$
- Consider region A_G s.t.:

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time

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m = 1

 $\delta = 0$

Consider region A_G s.t.:

 $(\delta, \varepsilon, t) \in A_G \iff G$ forms an (m, ε, δ) -group at time t

time



G = some of entites

 \mathbb{R}^1

m = 1

 $\delta > 0$

Consider region A_G s.t.:

 $(\delta, \varepsilon, t) \in A_G \iff G$ forms an (m, ε, δ) -group at time t



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time



G = some of entites

 \mathbb{R}^{d}

m = 1

 $\delta = 0$

Consider region A_G s.t.:

 $(\varepsilon, t) \in A_G \iff G$ forms an (m, ε, δ) -group at time t



3) How many combinatorially different group		
	\mathbb{R}^1	\mathbb{R}^{d}
#combinatorially diff. maximal groups	$O(n^4 au)$	
#maximal (<i>m</i> , ε , δ)-groups	$\Omega(n^3 au)$	$\Omega(n^3 \tau)$ [WADS 2013]

n = #trajectories $\tau =$ trajectory length

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	\mathbb{R}^1	\mathbb{R}^{d}
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n = #trajectories $\tau =$ trajectory length A = trajectory arrangement

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#combinatorially diff. maximal groups	$O(\mathcal{A} n^2)$	$O(n^4 aueta_4(n))$
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n = #trajectories $\tau =$ trajectory length $\mathcal{A} =$ trajectory arrangement $\beta_s(n) = \lambda_4(n)/n$

3) How many combinatorially different groups are there?			
	\mathbb{R}^1	\mathbb{R}^{d}	
#combinatorially diff. maximal groups	$O(\mathcal{A} n^2)$	$O(n^4 au eta_4(n))$	
#maximal (m, ε, δ)-groups	$\Omega(n^3 au)$	$\Omega(n^3 \tau)$ [WADS 2013]	
4) How do we compute them?			
Running time	$O(\mathcal{A} n^2\log^2 n)$	$O(n^4 aueta_4(n)\log^2 n)$	

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Running time	$O(\mathcal{A} n^2\log^2 n)$	$O(n^4 au eta_4(n) \log^2 n)$		

1) How do we represent the	em s.t. we can efficiently	change (n	n, ε, δ)?
		Update t	ime
Change parameters	$O(\log^c(n\tau) + k)$	VS	$O(\sqrt{g}\log^c(n au) +$

n = #trajectories $\tau =$ trajectory length $\mathcal{A} =$ trajectory arrangement $\beta_s(n) = \lambda_4(n)/n$ k = output size g = #maximal groups (for fixed ε)

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	\mathbb{R}^1	\mathbb{R}^{d}	
#combinatorially diff. maximal groups	$O(\mathcal{A} n^2)$	$O(n^4 aueta_4(n))$	
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Running time	$O(\mathcal{A} n^2\log^2 n)$	$O(n^4 aueta_4(n)\log^2 n)$	

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Update time			
Change parameters	$O(\log^c(n\tau) + k)$	VS	$O(\sqrt{g}\log^c(n\tau)+k)$
Thank you!			

n = #trajectories $\tau =$ trajectory length $\mathcal{A} =$ trajectory arrangement $\beta_s(n) = \lambda_4(n)/n$ k = output size g = #maximal groups (for fixed ε)

1) Tight bounds?

 $|\mathcal{G}|$

#maximal (m, ε, δ) -groups

 $\Omega(n^3\tau)$

 $O(n^4\tau)$

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 $|\mathcal{G}|$ $O(n^4\tau)$ #maximal (m, ε, δ) -groups $\Omega(n^3\tau)$ $O(n^3\tau)$

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1) Tight bounds?

$ \mathcal{G} $???	$O(n^4 \tau)$
#maximal (<i>m</i> , ε , δ)-groups	$\Omega(n^3 \tau)$	$O(n^3 \tau)$

2)

1) Tight bounds?

 $|\mathcal{G}|$??? $O(n^4\tau)$ #maximal (m, ε, δ) -groups $\Omega(n^3\tau)$ $O(n^3\tau)$

2) What if there are obstacles...?



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 $|\mathcal{G}|$??? $O(n^4\tau)$ #maximal (m, ε, δ) -groups $\Omega(n^3\tau)$ $O(n^3\tau)$

2) What if there are obstacles...?



3) What if we change the definition of group slightly....?

1) Tight bounds?



2) What if there are obstacles...?



3) What if we change the definition of group slightly....?

G = some of entites

 \mathbb{R}^1

m = 1

 $\delta = 0$

Consider region A_G s.t.:

 $(\varepsilon, t) \in A_G \iff G$ is ε -connected at time t



time



time

G = some of entites

 \mathbb{R}^1

 $\overline{m} = 1$ $\delta = 0$

Consider region A_G s.t.:

 $(\varepsilon, t) \in A_G \iff G$ is ε -connected at time t



G = some of entites

 \mathbb{R}^1

 $\overline{m} = 1$ $\delta = 0$

Consider region A_G s.t.:

 $(\varepsilon, t) \in A_{\mathcal{G}} \iff \mathcal{G}$ is ε -connected at time t





time

 \mathcal{H} = arrangement of functions h_a

 f_G is a monotone path in this arrangement



 \mathcal{H} = arrangement of functions h_a

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 f_G is a monotone path in this arrangement

Lemma. \mathcal{H} has complexity $O(|\mathcal{A}|n)$.

Lemma. Every vertex in \mathcal{H} can be in at most O(n) maximal groups.



 \mathcal{H} = arrangement of functions h_a

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 f_G is a monotone path in this arrangement

Lemma. \mathcal{H} has complexity $O(|\mathcal{A}|n)$.

Lemma. Every vertex in \mathcal{H} can be in at most O(n) maximal groups.

Theorem. The total complexity of all regions \mathcal{P}_G , over all sets G, is $O(|\mathcal{A}|n^2)$.

G = some of entites

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 $\overline{m} = 1$ $\delta = 0$

Consider region A_G s.t.:

 $(m, \delta, \varepsilon, t) \in A_G \iff G$ forms an (m, ε, δ) -group at time t

time



 \implies **Theorem.** The total complexity of all regions \mathcal{P}_G , over all sets G, is $O(|\mathcal{A}|n^2)$.









1) Construct \mathcal{H}





1) Construct \mathcal{H}

2) Use a sweepline algo to compute the regions





1) Construct \mathcal{H}

- 2) Use a sweepline algo to compute the regions
 - 2a) Figure out how to handle each event efficiently





1) Construct \mathcal{H}

2) Use a sweepline algo to compute the regions

2a) Figure out how to handle each event efficiently

Theorem. We can compute \mathcal{G} in $O(|\mathcal{A}|n^2 \log^2 n)$ time.

1) Tight bounds?

 $|\mathcal{G}|$

#maximal (m, ε, δ) -groups

 $\Omega(n^3\tau)$

 $O(n^4\tau)$

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 $|\mathcal{G}|$ $O(n^4\tau)$ #maximal (m, ε, δ) -groups $\Omega(n^3\tau)$ $O(n^3\tau)$

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 $|\mathcal{G}|$??? $O(n^4\tau)$ #maximal (m, ε, δ) -groups $\Omega(n^3\tau)$ $O(n^3\tau)$

Future Work/Open Problems1) Tight bounds? $|\mathcal{G}|$ $nimatical (m, \varepsilon, \delta)$ -groups $\Omega(n^3\tau)$ $O(n^3\tau)$



Lemma. \mathcal{H} has complexity $O(|\mathcal{A}|n)$.

 ${\mathcal E}$

Lemma. Every vertex in \mathcal{H} can be in at most O(n) maximal groups.

1) Tight bounds?

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